

# Luowei Zhou

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## EDUCATION

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### University of Michigan

Ann Arbor, Michigan, USA

*Ph.D. program in Robotics*

*Sept. 2015 – Present*

- **Research Interests:** Multi-modal embedding (vision and language), video understanding, deep learning
- **Courses:** Advanced Computer Vision, Natural Language Processing, Machine Learning, Optimization
- **Academics:** Curriculum GPA: **4.00/4.00**

### Nanjing University

Nanjing, Jiangsu, China

*Bachelor of Engineering in Automation*

*Sept. 2011 – Jun. 2015*

- **Courses:** Computer Vision, Artificial Intelligence, Advanced Programming Language, Data Structure
- **Academics:** Overall GPA: **91.8/100**, Major GPA: **93.0/100**

## PUBLICATIONS

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**L. Zhou, Y. Zhou, J. J. Corso, R. Socher and C. Xiong**, “*End-to-End Dense Video Captioning with Masked Transformer*”, CVPR 2018, accepted.

**L. Zhou, C. Xu and J. J. Corso**, “*Towards Automatic Learning of Procedures from Web Instructional Videos*”, AAI 2018, in press, **oral**. AR: 11%; h5: 56

**L. Zhou, C. Xu, P. Koch and J. J. Corso**, “*Watch What You Just Said: Image Captioning with Text-Conditional Attention*”, ACM Multimedia (Thematic Workshops) 2017: 305-313.

**L. Zhou, P. Yang, C. Chen and Y. Gao**, “*Multi-agent Reinforcement Learning with Sparse Interactions by Negotiation and Knowledge Transfer*”, IEEE Transactions on Cybernetics 2017, 47 (5): 1238 - 1250.

*SCI IF: 7.38; h5: 73*

**L. Zhou, P. Yang and C. Chen**, “*Multi-agent Reinforcement Learning with Sparse Interactions by Negotiation and Knowledge Transfer*”, IJCAI (Workshops) 2016, **oral**.

**L. Zhou, Y. Shi, J. Wang and P. Yang**, “*A Balanced Heuristic Mechanism for Multi-robot Task Allocation of Intelligent Warehouses*”, Mathematical Problems in Engineering 2014: 1–10. SCI IF: 0.80; h5: 39

## WORK EXPERIENCE

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### Salesforce Research (Metamind)

Palo Alto, California, USA

*Deep Learning Research Intern with Dr. Caiming Xiong and Dr. Richard Socher*

*May 2017 – Aug. 2017*

### University of Michigan, EECS

Ann Arbor, Michigan, USA

*Graduate Research Assistant with Prof. Jason Corso*

*April 2016 – Present*

## PROFESSIONAL ACTIVITIES

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*Co-organizer*, CVPR 2018 Workshop on Fine-grained Instructional Video Understanding, with Jason Corso, Josef Sivic and Ivan Laptev (accepted)

*Reviewer*, NIPS 2016, CVIU 2016, ICRA 2017, ITS 2017, TPAMI 2017

*Volunteer*, RSS 2016

*Attendee*, CVPR 2016, IJCAI 2016, ACM Multimedia 2017

## RESEARCH EXPERIENCE

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**Dense-Captioning Events in Video and Temporal Action Proposal** Salesforce Research  
*Supervisors: Dr. Caiming Xiong and Dr. Richard Socher* *May 2017 – Aug. 2017*

- Introduced a Self-attention-based video captioning model and improved our previously proposed action/event proposal network by carefully-designed Temporal Convolutional Networks
- Proposed to bridge event proposal and captioning by differentiable visual mask and achieved SotA results

**Large-scale Cooking Video Dataset for Procedure Learning and Recipe Generation** University of Michigan  
*Supervisor: Prof. Jason Corso* *Sept. 2016 – present*

- Introduced an event proposal network that can temporally localize procedure steps in web instructional videos and capture the structure of undergoing events in the videos
- Collected [YouCook2](#), which contains 2000 long videos with temporally localized recipe sentence annotations
- Current focuses: i) weakly supervised visual grounding from language description, ii) open-domain video event retrieval from language query

**Text-conditional Visual Captioning with Guiding Long Short-Term Memory** University of Michigan  
*Supervisor: Prof. Jason Corso* *Mar. 2016 – Nov. 2016*

- Proposed an encoder-decoder image captioning method though explicit text-conditional image guidance
- Extended the work to video captioning by leveraging audio features for extra guidance and achieved top performance in 2016 ACM Multimedia Video-to-Text Challenge

**End-to-End Grasping with Deep Reinforcement Learning** University of Michigan  
*Supervisor: Prof. Satinder Singh* *Sept. 2015 – Apr. 2016*

- Applied SotA Deep RL algorithm named Deep Q-network (DQN) to robot grasping tasks
- Built an API between physics engine MuJoCo and the DQN module

**Research on Multi-Agent Reinforcement Learning with Sparse Interactions** Nanjing University  
*Supervisors: Prof. Chunlin Chen and Dr. Pei Yang* *Dec. 2014 – Jul. 2015*

- Incorporated the concept of equilibrium to traditional sparse-interaction-based MARL algorithms
- Decomposed the MARL problem from behavioristics prospective and proposed to transfer the knowledge from the environment and pre-trained coordination Q-value tables to the joint-state Q table
- First to apply MARL with sparse interactions in the real-world scenario (intelligent warehouse systems)

**Multi-Robot Task Allocation and Path Planning in Dynamic Environments** Nanjing University  
*Supervisor: Dr. Pei Yang* *Nov. 2013 – Jul. 2014*

- Proposed a Balanced Heuristic Mechanism to balance task allocation in multi-robot systems
- Built an intelligent warehouse simulator from scratch using C/OpenGL for the experiments

## HONORS AND AWARDS

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*Outstanding Winner Awards (0.2%), Mathematical Contest in Modeling (MCM)* 2013  
*Sienhua New and Tsu Way Shen Memorial Award (Top 1), of University of Michigan* 2015  
*Best Undergrad Thesis (Top 1), of Jiangsu Province* 2015  
*National Scholarship (1%), of Nanjing University* 2012

## PROFICIENCY AND SKILLS

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*Technical Skills:* PyTorch/Torch, Python, C/C++, Linux, Git, LaTeX, Matlab, Caffe, HTML  
*Languages:* English (proficient) and Chinese (native)